

4-1-2013

# Full Superposition Principle Is Inconsistent with Non-Deterministic Versions of Quantum Physics

Andres Ortiz

*University of Texas at El Paso*, aortiz19@miners.utep.edu

Vladik Kreinovich

*University of Texas at El Paso*, vladik@utep.edu

Follow this and additional works at: [http://digitalcommons.utep.edu/cs\\_techrep](http://digitalcommons.utep.edu/cs_techrep)



Part of the [Computer Sciences Commons](#), and the [Physics Commons](#)

Comments:

Technical Report: UTEP-CS-13-08b

---

## Recommended Citation

Ortiz, Andres and Kreinovich, Vladik, "Full Superposition Principle Is Inconsistent with Non-Deterministic Versions of Quantum Physics" (2013). *Departmental Technical Reports (CS)*. Paper 745.

[http://digitalcommons.utep.edu/cs\\_techrep/745](http://digitalcommons.utep.edu/cs_techrep/745)

This Article is brought to you for free and open access by the Department of Computer Science at DigitalCommons@UTEP. It has been accepted for inclusion in Departmental Technical Reports (CS) by an authorized administrator of DigitalCommons@UTEP. For more information, please contact [lweber@utep.edu](mailto:lweber@utep.edu).

# FULL SUPERPOSITION PRINCIPLE IS INCONSISTENT WITH NON-DETERMINISTIC VERSIONS OF QUANTUM PHYSICS

Andres Ortiz<sup>1,2</sup> and Vladik Kreinovich<sup>3</sup>

<sup>1</sup>Department of Mathematical Sciences

<sup>2</sup>Department of Physics

<sup>3</sup>Department of Computer Science

University of Texas at El Paso

El Paso, TX 79968, USA

contact email vladik@utep.edu

## Abstract

Many practical systems are non-deterministic, in the sense that available information about the initial states and control values does not uniquely determine the future states. For some such systems, it is important to take quantum effects into account. For that, we need to develop non-deterministic versions of quantum physics. In this paper, we show that for non-deterministic versions of quantum physics, we cannot require *superposition principle* – one of the main fundamental principles of modern quantum mechanics. Specifically, while we can consider superpositions of states corresponding to the same version of the future dynamics, it is not consistently possible to consider superpositions of states corresponding to different versions of the future.

## Why non-deterministic versions of quantum physics.

Traditional control theory has been developed to control deterministic systems, in which the initial state and the control values uniquely determine all future states of the system. In many practical situations, however, physical systems are non-deterministic – e.g., as a result of partial observability of events. Special modifications of traditional control techniques have been invented for such non-deterministic systems; see, e.g., [Ramadge and Wonham, 1987; Overkamp, 1994; Heymann and Lin, 1998] and references therein.

In many practical situations, we need to take quantum effects into account. For non-deterministic systems, this means that we need to consider non-deterministic versions of quantum physics. The usual quantum physics is deterministic, in the sense that once we know the initial state  $\psi(t_0)$ , we can uniquely predict the state  $\psi(t)$  at any future moment of time  $t > t_0$  and thus, we can uniquely predict the probabilities of different future measurement results. It is therefore necessary to con-

sider *non-deterministic* versions of quantum physics, in which for the same initial state  $\psi(t_0)$  we may have several different possible states  $\psi(t) \neq \psi'(t)$  at a future moment of time  $t$ .

## How to describe non-deterministic versions of quantum physics: superposition principle.

How can we describe non-deterministic versions of quantum physics? It is definitely necessary to make sure that this description satisfies fundamental principles of quantum physics. One of such fundamental principles is the *superposition principle*. There are many ways to formulate this principle. To be able to apply it to non-deterministic situations, let us formulate this principle in such a way that would not depend on the deterministic character of dynamics.

The traditional formulations of the superposition principle use the fact that the states  $\psi$  of a quantum system are unit vectors in a complex-valued Hilbert space. In the non-relativistic quantum mechanics, which studies systems with a fixed number of particles, states are complex-valued functions  $\psi(x)$  for which  $\int |\psi(x)|^2 dx = 1$ . In relativistic quantum mechanics, the basis of the corresponding Hilbert space include states corresponding to different number of particles; in quantum field theory, states are even more complicated – since they describe fields. In all these cases, we have a Hilbert space, i.e., a linear space in which addition of elements (vectors) and multiplication of its elements by a complex number are well defined, and there is a (bilinear) form  $\langle x, y \rangle$  for which:

- $\langle a \cdot x + a' \cdot x', y \rangle = a \cdot \langle x, y \rangle + a' \cdot \langle x', y \rangle$ ,
- $\langle x, a \cdot y + a' \cdot y' \rangle = \bar{a} \cdot \langle x, y \rangle + \bar{a}' \cdot \langle x, y' \rangle$   
(where  $\bar{z}$  means complex conjugate),
- $\langle y, x \rangle = \overline{\langle x, y \rangle}$ ,
- $\langle x, x \rangle = 0$ , and

- $\langle x, x \rangle > 0$  for  $x \neq 0$ .

The bilinear norm defines a *norm*  $\|x\| \stackrel{\text{def}}{=} \sqrt{\langle x, x \rangle}$ .

**Definition 1.** Let  $H$  be a Hilbert space. By a state, we mean a unit vector in  $H$ .

In these terms, the superposition principle can be formulated as follows. Let  $\psi(t_0)$  and  $\psi'(t_0)$  be states for which the quantum physics predicts future states  $\psi(t)$  and  $\psi'(t)$ , and let  $a$  and  $a'$  be complex numbers for which

$$\psi''(t_0) \stackrel{\text{def}}{=} a \cdot \psi(t_0) + a' \cdot \psi'(t_0)$$

is also a state. Then, if we start with the initial state  $\psi''(t_0)$ , at the moment  $t > t_0$ , we get a state

$$\psi''(t) = a \cdot \psi(t) + a' \cdot \psi'(t).$$

In physical terms, superposition principle means that if we start with a superposition

$$\psi''(t_0) = a \cdot \psi(t_0) + a' \cdot \psi'(t_0)$$

of the states  $\psi(t_0)$  and  $\psi'(t_0)$ , then at every future moment of time  $t > t_0$ , we still get a superposition

$$\psi''(t) = a \cdot \psi(t) + a' \cdot \psi'(t)$$

of the corresponding states  $\psi(t_0)$  and  $\psi'(t_0)$ .

It is sufficient to restrict ourselves to the case when the states  $\psi(t_0)$  and  $\psi'(t_0)$  are orthogonal to each other:  $\psi(t_0) \perp \psi'(t_0)$ , i.e.,  $\langle \psi(t_0), \psi'(t_0) \rangle = 0$ . In this case, the requirement that a linear combination

$$a \cdot \psi(t_0) + a' \cdot \psi'(t_0)$$

is also a state – i.e., that it is a unit vector – means that

$$|a|^2 \cdot \|\psi(t_0)\|^2 + |a'|^2 \cdot \|\psi'(t_0)\|^2 = |a|^2 + |a'|^2 = 1.$$

The above formulation assumes that the future state is uniquely determined by the original state. To be able to apply this principle to possible non-deterministic versions of quantum physics, we need to reformulate this principle in such a way that it does not depend on whether the underlying theory is deterministic or not.

In a non-deterministic theory, a state  $\psi_0$  at the moment  $t_0$  does not, in general, uniquely determine the state  $\psi_1$  at the moment  $t > t_0$ ; for each  $\psi_0$ , we may have different states  $\psi_1$ . A theory must then describe which pairs  $(\psi_0, \psi_1)$  are possible and which are not. The only restriction is that for each initial state  $\psi_0$ , we must have at least one possible future state  $\psi_1$ . Thus, we arrive at the following definition:

**Definition 2.** Let  $t_0 < t_1$  be two real numbers; these numbers will be called moments of time.

- By dynamics  $D(t_0 \rightarrow t_1)$  corresponding to these two moments of time, we mean a set of pairs of states  $(\psi_0, \psi_1)$  such that for every state  $\psi_0$ , there is a state  $\psi_1$  for which  $(\psi_0, \psi_1) \in D(t_0 \rightarrow t_1)$ .
- When  $(\psi_0, \psi_1) \in D(t_0 \rightarrow t_1)$ , we say that it is possible to have a state  $\psi_0$  at moment  $t_0$  and a state  $\psi_1$  at moment  $t_1$ , or, in short, that a transition from  $\psi_0$  to  $\psi_1$  is possible. Alternatively, we will denote the possibility of such a transition as  $\psi_0 \rightarrow \psi_1$ .

In the traditional (deterministic) quantum physics, where the next state  $\psi_1$  is uniquely determined by the previous state  $\psi_0$  as  $\psi_1 = U\psi_0$  for an appropriate operator  $U$ , the above-defined dynamics takes the form  $D(t_0 \rightarrow t_1) = \{(\psi_0, U\psi_0)\}$ , i.e., it coincides with the (graph of) the operator  $U$ .

**Definition 3.** We say that a dynamics  $D(t_0 \rightarrow t_1)$  is deterministic if for every state  $\psi_0$ , there exists exactly one state  $\psi_1$  for which a transition from  $\psi_0$  to  $\psi_1$  is possible.

In the general (not necessarily deterministic) case, it is natural to formulate the superposition principle as follows:

**Definition 4.** We say that a dynamics  $D(t_0 \rightarrow t_1)$  satisfies the superposition principle if it satisfies the following property: for every four states  $\psi_0 \perp \psi'_0$ ,  $\psi_1$ , and  $\psi'_1$  for which transitions from  $\psi_0$  to  $\psi_1$  and from  $\psi'_0$  to  $\psi'_1$  are possible, and for every two complex numbers  $a$  and  $a'$  for which  $|a|^2 + |a'|^2 = 1$ , the combination  $\psi''_1 = a \cdot \psi_1 + a' \cdot \psi'_1$  is also a state, and a transition from  $\psi''_0 = a \cdot \psi_0 + a' \cdot \psi'_0$  to  $\psi''_1$  is also possible.

*Comment.* For the deterministic case, this formulation is equivalent to the above-presented usual formulation of the superposition principle.

**Main result.** Here is our unexpected result:

**Theorem.** If a dynamics  $D(t_0 \rightarrow t_1)$  satisfies the superposition principle, then it is deterministic.

**Proof.** Let us assume that the dynamics  $D(t_0 \rightarrow t_1)$  satisfies the superposition principle. We will prove that for any state  $\psi_0$ , if there is a transition from  $\psi_0$  to  $\psi_1$  and a transition from  $\psi_0$  to  $\varphi_1$ , then  $\psi_1 = \varphi_1$ .

To prove this, let us select any unit vector orthogonal to  $\psi_0$  and denote it by  $\psi'_0$ . By definition of the dynamics, there exists at least one state for which a transition from  $\psi'_0$  to this state is possible; let us select one of these states and denote it by  $\psi'_1$ .

By superposition principle, since the vectors  $\psi_0$  and  $\psi'_0$  are orthogonal, and since it is possible to have tran-

sitions  $\psi_0 \rightarrow \psi_1$  and  $\psi'_0 \rightarrow \psi'_1$ , the transition

$$\varphi_+ \stackrel{\text{def}}{=} \frac{1}{\sqrt{2}} \cdot \psi_0 + \frac{1}{\sqrt{2}} \cdot \psi'_0 \rightarrow \frac{1}{\sqrt{2}} \cdot \psi_1 + \frac{1}{\sqrt{2}} \cdot \psi'_1 \quad (1)$$

is also possible. Similarly, since it is possible to have transitions  $\psi_0 \rightarrow \varphi_1$  and  $\psi'_0 \rightarrow \psi'_1$ , the transition

$$\varphi_- \stackrel{\text{def}}{=} \frac{1}{\sqrt{2}} \cdot \psi_0 - \frac{1}{\sqrt{2}} \cdot \psi'_0 \rightarrow \frac{1}{\sqrt{2}} \cdot \varphi_1 - \frac{1}{\sqrt{2}} \cdot \psi'_1 \quad (2)$$

is also possible.

One can easily check that the vectors

$$\varphi_+ = \frac{1}{\sqrt{2}} \cdot \psi_0 + \frac{1}{\sqrt{2}} \cdot \psi'_0 \quad \text{and} \quad \varphi_- = \frac{1}{\sqrt{2}} \cdot \psi_0 - \frac{1}{\sqrt{2}} \cdot \psi'_0$$

are orthogonal, and that

$$\frac{1}{\sqrt{2}} \cdot \varphi_+ + \frac{1}{\sqrt{2}} \cdot \varphi_- = \frac{1}{\sqrt{2}} \cdot \left( \frac{1}{\sqrt{2}} \cdot \psi_0 + \frac{1}{\sqrt{2}} \cdot \psi'_0 \right) +$$

$$\frac{1}{\sqrt{2}} \cdot \left( \frac{1}{\sqrt{2}} \cdot \psi_0 - \frac{1}{\sqrt{2}} \cdot \psi'_0 \right) =$$

$$\left( \frac{1}{2} + \frac{1}{2} \right) \cdot \psi_0 + \left( \frac{1}{2} - \frac{1}{2} \right) \cdot \psi'_0 = \psi_0.$$

Thus, from the possibility of the transitions (1) and (2), by using the superposition principle, we can conclude that

$$\psi_0 \rightarrow \frac{1}{\sqrt{2}} \cdot \left( \frac{1}{\sqrt{2}} \cdot \psi_1 + \frac{1}{\sqrt{2}} \cdot \psi'_1 \right) +$$

$$\frac{1}{\sqrt{2}} \cdot \left( \frac{1}{\sqrt{2}} \cdot \varphi_1 - \frac{1}{\sqrt{2}} \cdot \psi'_1 \right) =$$

$$\frac{1}{2} \cdot \psi_1 + \frac{1}{2} \cdot \varphi_1 + \frac{1}{2} \cdot \psi'_1 - \frac{1}{2} \cdot \psi'_1 = \frac{1}{2} \cdot \psi_1 + \frac{1}{2} \cdot \varphi_1.$$

Thus, the combination

$$s \stackrel{\text{def}}{=} \frac{1}{2} \cdot \psi_1 + \frac{1}{2} \cdot \varphi_1$$

should be a state, i.e., a unit vector in the Hilbert space. It is known that in a Hilbert space (just like in a Euclidean space), for every two vectors  $x$  and  $y$ , we have

$\|x + y\| \leq \|x\| + \|y\|$ , and the only possibility to have  $\|x + y\| = \|x\| + \|y\|$  is when the vectors are collinear, i.e., when  $y = \lambda \cdot x$  for some  $\lambda > 0$ . For  $x = \frac{1}{2} \cdot \psi_1$  and  $y = \frac{1}{2} \cdot \varphi_1$ , we have

$$\|x\| = \frac{1}{2} \cdot \|\psi_1\| = \frac{1}{2}, \quad \|y\| = \frac{1}{2} \cdot \|\varphi_1\| = \frac{1}{2},$$

and thus,  $1 = \|s\| = \|x + y\| = \|x\| + \|y\|$ . So, we conclude that  $y = \lambda \cdot x$  for some  $\lambda > 0$ . For the norms, we thus have  $\|y\| = \lambda \cdot \|x\|$  and, since  $\|x\| = \|y\| = \frac{1}{2}$ ,

we conclude that  $\lambda = 1$  and  $y = x$ . From  $y = \frac{1}{2} \cdot \varphi_1 = \frac{1}{2} \cdot \psi_1 = x$ , we conclude that  $\psi_1 = \varphi_1$ . The statement is proven.

**Discussion.** In the traditional (deterministic) quantum physics, all the future states correspond to a single version of the future. Superposition principle enables us to consider superpositions of such states. The fact that numerous experiments confirm the predictions of quantum physics support such superpositions.

When we go from the traditional (deterministic) quantum physics to a non-deterministic version, we also add states corresponding to alternative versions of the future. At first glance, it seems reasonable to extend the usual superposition principle to such states, and to allow not only superpositions of states from the same version of the future, but also superpositions of states from different alternative futures. Our result shows that such an extension is not possible: it is not possible to consider superpositions of states corresponding to different alternative futures. In other words, to consider non-deterministic version of quantum physics, we have to impose restrictions on the superposition principle.

*Philosophical comment.* Our motivation was based on potential control applications; however, this result may also be of foundational interest, since some researchers consider non-determinism to be a natural consequence of the intuitive idea of freedom of will.

**Acknowledgments.** This work was supported in part by the National Science Foundation grants HRD-0734825 and HRD-1242122 (Cyber-ShARE Center of Excellence) and DUE-0926721, by Grants 1 T36 GM078000-01 and 1R43TR000173-01 from the National Institutes of Health, and by a grant on F-transforms from the Office of Naval Research. The authors are thankful to the anonymous referees for valuable suggestions.

## References

Feynman, R., Leighton, R., and Sands, M. (2005) *The Feynman Lectures on Physics*, Addison Wesley, Boston, Massachusetts.

- Heymann, M., Lin, F. (1998) Discrete-event control of nondeterministic systems", *IEEE Transactions on Automatic Control* **43**(1), pp. 3–17.
- Overkamp, A. (1994) Supervisory control for nondeterministic systems, *Proceedings of the 11th International Conference on Analysis and Optimization of Systems: Discrete Event Systems*, Springer Lecture Notes in Control and Information Sciences **199**, pp. 59–65.
- Ramadge, P.J., Wonham, W.M.(1987) Supervisory control of a class of discrete event processes, *SIAM J. Control Optim.* **25**(1), pp. 206–230.