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From Processing Interval-Valued Fuzzy Data to General Type-2: Towards Fast Algorithms

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Abstract—It is known that processing of data under general type-1 fuzzy uncertainty can be reduced to the simplest case – of interval uncertainty: namely, Zadeh’s extension principle is equivalent to level-by-level interval computations applied to α-cuts of the corresponding fuzzy numbers.

However, type-1 fuzzy numbers may not be the most adequate way of describing uncertainty, because they require that an expert can describe his or her degree of confidence in a statement by an exact value. In practice, it is more reasonable to expect that the expert estimates his or her degree by using imprecise words from natural language – which can be naturally formalized as fuzzy sets. The resulting type-2 fuzzy numbers more adequately represent the expert’s opinions, but their practical use is limited by the seeming computational complexity of their use. It turns out that for the practically important case of interval-valued fuzzy sets, processing such sets can also be reduced to interval computations – and that this idea can be naturally extended to arbitrary type-2 fuzzy numbers.

I. Knowledge Processing and Fuzzy Uncertainty

A. Need to Process Fuzzy Uncertainty

In many practical situations, we only have expert estimates for the inputs \( x_i \). Sometimes, experts provide guaranteed bounds on \( x_i \), and even the probabilities of different values within these bounds. However, such cases are rare. Usually, the experts’ opinion about the uncertainty of their estimates are described by (imprecise, “fuzzy”) words from natural language. For example, an expert can say that the value \( x_i \) of the \( i \)-th quantity is approximately equal to 1.0, with an accuracy most probably about 0.1. Based on such “fuzzy” information, what can we say about \( y = f(x_1, \ldots, x_n) \)?

The need to process such “fuzzy” information was first emphasized in the early 1960s by L. Zadeh who designed a special technique of fuzzy logic for such processing; see, e.g., [3], [14]. In this technique, our imprecise knowledge about \( x_i \) is described by assigning, to each possible real value \( x_i \), the degree \( m_i(x_i) \in [0, 1] \) with which this value is a possible value of the \( i \)-th input.

In most practical situations, the membership function starts with 0, continuously increases until a certain value and then continuously decreases to 0. Such membership function describe usual expert’s expressions such as “small”, “medium”, “reasonably high”, “approximately equal to \( a \) with an error about \( \sigma \)”, etc. Since membership functions of this type are actively used in expert estimates of number-valued quantities, they are usually called fuzzy numbers.

B. Zadeh’s Extension Principle

Let us recall how fuzzy techniques can be used for processing fuzzy uncertainty.

We know an algorithm \( y = f(x_1, \ldots, x_n) \) that relates the value of the desired difficult-to-estimate quantity \( y \) with the values of easier-to-estimate auxiliary quantities \( x_1, \ldots, x_n \). We also have expert knowledge about each of the quantities \( x_i \). For each \( i \), this knowledge is described in terms of the corresponding membership function \( m_i(x_i) \). Based on this information, we want to find the membership function \( m(y) \) which describes, for each real number \( y \), the degree of confidence that this number is a possible value of the desired quantity.

Intuitively, \( y \) is a possible value of the desired quantity if for some values \( x_1, \ldots, x_n \), \( x_1 \) is a possible value of the 1st input quantity, and \( x_2 \) is a possible value of the 1st input quantity, \( \ldots \), and \( y = f(x_1, \ldots, x_n) \). We know that the degree of confidence that \( x_1 \) is a possible value of the 1st input quantity is equal to \( m_1(x_1) \), that the degree of confidence that \( x_2 \) is a possible value of the 2nd input quantity is equal to \( m_2(x_2) \), etc. The degree of confidence \( d(y, x_1, \ldots, x_n) \) in an equality \( y = f(x_1 \ldots, x_n) \) is, of course, equal to 1 if this equality holds, and to 0 if this equality does not hold.

The simplest way to represent “and” is to use \( \min \). Thus, for each combination of values \( x_1, \ldots, x_n \), the degree of confidence in a composite statement “\( x_1 \) is a possible value of the 1st input quantity, and \( x_2 \) is a possible value of the 1st input quantity, \( \ldots \), and \( y = f(x_1 \ldots, x_n) \)” is equal to

\[
\min(m_1(x_1), m_2(x_2), \ldots, d(y, x_1, \ldots, x_n)).
\]

We can simplify this expression if we consider two possible cases: when the equality \( y = f(x_1, \ldots, x_n) \) holds, and when this equality does not hold.

When the equality \( y = f(x_1, \ldots, x_n) \) holds, we get \( d(y, x_1, \ldots, x_n) = 1 \), and thus, the above degree of confidence is simply equal to

\[
\min(m_1(x_1), m_2(x_2), \ldots, d(y, x_1, \ldots, x_n)).
\]

When the equality \( y = f(x_1, \ldots, x_n) \) does not hold, we get \( d(y, x_1, \ldots, x_n) = 0 \), and thus, the above degree of confidence is simply equal to 0.

We want to combine these degrees of belief into a single degree of confidence that “for some values \( x_1, \ldots, x_n \), \( x_1 \) is
a possible value of the 1st input quantity, and \( x_2 \) is a possible value of the 1st input quantity, \( \ldots \), and \( y = f(x_1, \ldots, x_n) \). The words “for some values \( x_1, \ldots, x_n \)” means that the following composite property hold either for one combination of real numbers \( x_1, \ldots, x_n \), or from another combination – until we exhaust all (infinitely many) such combinations. The simplest way to represent “or” is to use \( \max \). Thus, the desired degree of confidence \( m(y) \) is equal to the maximum of the degrees corresponding to different combinations \( x_1, \ldots, x_n \).

Since we have infinitely many possible combinations, maximum is not necessarily attained, so we should, in general, consider supremum instead of the maximum:

\[
m(y) = \sup \min(m_1(x_1), m_2(x_2), \ldots, d(y, x_1, \ldots, x_n)),
\]

where the supremum is taken over all possible combinations.

Since we know that the maximized degree is non-zero only when \( y = f(x_1, \ldots, x_n) \), it is sufficient to only take supremum over such combinations. For such combinations, we can omit the term \( d(y, x_1, \ldots, x_n) \) in the maximized expression, so we arrive at the following formula:

\[
m(y) = \sup \{\min(m_1(x_1), m_2(x_2), \ldots) : y = f(x_1, \ldots, x_n)\}.
\]

This formula describes a reasonable way to extend an arbitrary data processing algorithm \( f(x_1, \ldots, x_n) \) from real-valued inputs to a more general case of fuzzy inputs. It was first proposed by L. Zadeh and is thus called Zadeh’s extension principle. This is the main formula that describes knowledge processing under fuzzy uncertainty.

C. Reduction to Interval Computations

It is known that from the computational viewpoint, the application of this formula can be reduced to interval computations – and indeed, this is how knowledge processing under fuzzy uncertainty is usually done, by using this reduction; see, e.g., [3], [10], [14].

Specifically, for each fuzzy set with a membership function \( m(x) \) and for each \( \alpha \in (0, 1] \), we can define this set’s \( \alpha \)-cut as \( \mathbf{x}(\alpha) = \{x : m(x) \geq \alpha\} \). Vice versa, if we know the \( \alpha \)-cuts for all \( \alpha \), we, for each \( x \), can reconstruct the value \( m(x) \) as the largest value \( \alpha \) for which \( x \in \mathbf{x}(\alpha) \).

It is known that when the inputs \( m_i(x_i) \) are fuzzy numbers, and the function \( y = f(x_1, \ldots, x_n) \) is continuous, then for each \( \alpha \), the \( \alpha \)-cut \( \mathbf{y}(\alpha) \) of \( y \) is equal to the range of possible values of \( f(x_1, \ldots, x_n) \) when \( x_i \in \mathbf{x}_i(\alpha) \) for all \( i \):

\[
\mathbf{y}(\alpha) = f(\mathbf{x}_1(\alpha), \ldots, \mathbf{x}_n(\alpha)).
\]

Thus, from the computational viewpoint, the problem of processing data under fuzzy uncertainty can be reduced to several problems of interval computing under uncertainty – as many problems as there are \( \alpha \)-levels.

There exist many efficient algorithms and software packages for solving interval computations problems; see, e.g., [1], [2], [8] and references therein. So, the above reduction can help to efficiently solve the fuzzy data processing as well.

II. TYPE-2 FUZZY SETS

A. Need for Type-2 Fuzzy Sets

The main objective of fuzzy logic is to describe uncertain (“fuzzy”) knowledge, when an expert cannot describe his or her knowledge by an exact value or by a precise set of possible values. Instead, the expert describe this knowledge by using words from natural language. Fuzzy logic provides a procedure for formalizing these words into a computer-understandable form – as “fuzzy sets.”

In the traditional approach to fuzzy logic, the expert’s degree of certainty in a statement – such as the value \( m_A(x) \) describing that the value \( x \) satisfies the property \( A \) (e.g., “small”) – is described by a number from the interval \([0, 1]\). However, we are considering situations in which an expert is unable to describe his or her knowledge in precise terms. It is not very reasonable to expect that in this situation, the same expert will be able to meaningfully express his or her degree of certainty by a precise number. It is much more reasonable to assume that the expert will describe these degrees also by words from natural language.

Thus, for every \( x \), a natural representation of the degree \( m(x) \) is not a number, but rather a new “fuzzy” set. Such situations, in which to every value \( x \) we assign a fuzzy number \( m(x) \), are called type-2 fuzzy sets.

B. Successes of Type-2 Fuzzy Sets

Type-2 fuzzy sets are actively used in practice; see, e.g., [5], [6], [7]. Since type-2 fuzzy sets provide a more adequate representation of expert knowledge, it is not surprising that such sets lead to a higher quality control, higher quality clustering, etc., in comparison with the more traditional type-1 sets.

C. The Main Obstacle to Using Type-2 Fuzzy Sets

If type-2 fuzzy sets are more adequate, why are not they used more? The main reason why their use is limited is that the transition from type-1 to type-1 fuzzy sets leads to an increase in computation time. Indeed, to describe a traditional (type-1) membership function function, it is sufficient to describe, for each value \( x \), a single number \( m(x) \). In contrast, to describe a type-2 set, for each value \( x \), we must describe the entire membership function – which needs several parameters to describe. Since we need more numbers just to store such information, we need more computational time to process all the numbers representing these sets.

D. Interval-Valued Fuzzy Sets

In line with this reasoning, the most widely used type-2 fuzzy sets are the ones which require the smallest number of parameters to store. We are talking about “interval-valued” fuzzy numbers, in which for each \( x \), the degree of certainty \( m(x) \) is an interval \([\underline{m}(x), \overline{m}(x)]\). To store each interval, we need exactly two numbers – the smallest possible increase over the single number needed to store the type-1 value \( m(x) \).
III. Towards Fast Algorithms for Processing Interval-Valued Fuzzy Data

In their papers and books, J. M. Mendel and his co-authors provided new algorithms which drastically reduced the computational complexity of processing interval-valued fuzzy data; see, e.g., [5], [6], [7] and references therein. In particular, they showed that processing interval-valued fuzzy data can be efficiently reduced to interval computations. Since there exist many efficient algorithms and software packages for solving interval computation problems, this reduction means that we can use these packages to also process interval-valued fuzzy data – and thus, that processing interval-valued fuzzy data is (almost) as efficient as processing the traditional (type-1) fuzzy data.

The corresponding reduction can be explained as follows. In the case of interval-valued fuzzy data, we do not know the exact numerical values $m_i(x_i)$ of the membership functions, we only know the interval $\mathbf{m}_i(x) = [m_i(x), \overline{m}_i(x)]$ of possible values of $m_i(x_i)$. By applying Zadeh’s extension principle to different combinations of values $m_i(x_i) \in [m_i(x), \overline{m}_i(x)]$, we can get, in general, different values of

$$y = f(x_1, \ldots, x_n);$$

$$\overline{m}(y) = \sup \{\min(\overline{m}_1(x_1), \overline{m}_2(x_2), \ldots) : y = f(x_1, \ldots, x_n)\}. $$

In other words,

- to compute the lower membership function $m(y)$, it is sufficient to apply the standard Zadeh’s extension principle to the lower membership functions $m_i(x_i)$, and
- to compute the upper membership function $\overline{m}(y)$, it is sufficient to apply the standard Zadeh’s extension principle to the upper membership functions $\overline{m}_i(x_i)$.

We already know that for type-1 fuzzy sets, Zadeh’s extension principle can be reduced to interval computations. Thus, we conclude that for every level $\alpha \in (0, 1)$, we have

$$\underline{x}(\alpha) = f(\underline{x}_1(\alpha), \ldots, \underline{x}_n(\alpha))$$

and

$$\overline{x}(\alpha) = f(\overline{x}_1(\alpha), \ldots, \overline{x}_n(\alpha)),$$

where

$$\underline{x}_i = \{x_i : m_i(x_i) \geq \alpha\} \text{ and } \overline{x}_i = \{x_i : \overline{m}_i(x_i) \geq \alpha\}.$$  

IV. Extension to General Type-2 Fuzzy Numbers

Let us show that the above techniques can be extended beyond interval-valued fuzzy numbers, to arbitrary type-2 fuzzy numbers; see, e.g., [4]. Indeed, for arbitrary type-2 fuzzy numbers, for each $x_i$, the value $m_i(x_i)$ is also a fuzzy number.

The relation between the input fuzzy numbers $m_i(x_i)$ and the desired fuzzy number $m(y)$ can be expressed by the same Zadeh’s principle:

$$y = f(x_1, \ldots, x_n);$$

$$\overline{m}(y) = \sup \{\min(\overline{m}_1(x_1), \overline{m}_2(x_2), \ldots) : y = f(x_1, \ldots, x_n)\},$$

but this time, all the values $m_i(x_i)$ and $m(y)$ are fuzzy numbers. How can we describe this relation between fuzzy numbers?

Let us first describe the fuzzy numbers themselves. By definition, a fuzzy number is a function that maps every possible value to a degree from the interval $[0, 1]$ describing to what extend this value is possible. Thus, e.g., for each $y$, the corresponding fuzzy number $m(y)$ is a mapping which maps all possible values $t \in [0, 1]$ into a degree (from the interval $[0, 1]$) with which $t$ is a possible value of $m(y)$. Let us denote this degree by $m(y, t)$.

Similarly, for each $i$ and for each real number $x_i$, the fuzzy number $m_i(x_i)$ is a mapping which maps all possible values $t \in [0, 1]$ into a degree (from the interval $[0, 1]$) with which $t$ is a possible value of $m_i(x_i)$. Let us denote this degree by $m_i(x_i, t)$.

As we have already mentioned, processing fuzzy numbers can be reduced to processing the corresponding $\alpha$-cuts. In this case, all the values $m_i(x_i)$ and $m(y)$ are fuzzy numbers, we conclude that, for every $\alpha \in [0, 1]$, the $\alpha$-cut $(m(y))(\alpha)$ for the fuzzy number $m(y)$ can be obtained by processing the
corresponding $\alpha$-cuts $(m(y))(\alpha)$ for $m_i(x_i)$. To avoid confusion between standard $\alpha$-cuts, let us denote the corresponding threshold not as $\alpha$ but as $\beta$. As a result, we conclude that

$$m(y)(\beta) = \sup\{\min(m_1(x_1)(\beta), m_2(x_2)(\beta), \ldots) : y = f(x_1, \ldots, x_n)\}.$$  

For fuzzy numbers, the corresponding $\beta$-cuts are intervals:

$$m(y)(\beta) = [m(y)(\beta), \overline{m(y)(\beta)}]$$

and

$$m_i(x_i)(\beta) = [m_i(x_i)(\beta), m_i(x_i)(\beta)].$$

From our description of the interval-valued fuzzy case, we already know that in the interval case, since the expression corresponding to Zadeh’s extension principle is monotonic,

- the lower endpoints of the output can be obtained from the lower endpoints of the inputs, and
- the upper endpoint of the output can be obtained from the upper endpoints of the inputs,

hence, that

$$m(y)(\beta) = \sup\{\min(m_1(x_1)(\beta), m_2(x_2)(\beta), \ldots) : y = f(x_1, \ldots, x_n)\};$$

$$m(y)(\beta) = \sup\{\min(m_1(x_1)(\beta), m_2(x_2)(\beta), \ldots) : y = f(x_1, \ldots, x_n)\}.$$

For the corresponding functions

$$m(y)(\beta), m_1(x_1)(\beta), m_2(x_2)(\beta), m_i(x_i)(\beta),$$

we get the standard Zadeh’s extension principle relation between membership functions. We already know that this relation can be described in terms of interval computations. Thus, we conclude that

$$\underline{y}(\alpha, \beta) = f(\underline{x}_1(\alpha, \beta), \ldots, \underline{x}_n(\alpha, \beta))$$

and

$$\overline{y}(\alpha, \beta) = f(\overline{x}_1(\alpha, \beta), \ldots, \overline{x}_n(\alpha, \beta)),$$

where

$$\underline{y}(\alpha, \beta) = \{x : y(\beta) \geq \alpha\} \text{ and } \overline{y}(\alpha, \beta) = \{x : \overline{y}(\beta) \geq \alpha\}$$

are the $\alpha$-cuts of the corresponding membership functions

$$\underline{m}(y)(\beta) \text{ and } \overline{m}(y)(\beta),$$

and similarly,

$$\underline{x}_i(\alpha, \beta) = \{x_i : x_i(\beta) \geq \alpha\} \text{ and } \overline{x}_i(\alpha, \beta) = \{x_i : \overline{x}_i(\beta) \geq \alpha\}$$

are the $\alpha$-cuts of the corresponding membership functions

$$\underline{m}(x_i)(\beta) \text{ and } \overline{m}(x_i)(\beta).$$

Thus, from the computational viewpoint, the problem of processing data under type-2 fuzzy uncertainty can be reduced to several problems of data processing under interval uncertainty – as many problems as there are $(\alpha, \beta)$-levels.

V. CONCLUSION

Type-2 fuzzy sets more adequately describe expert’s opinion than the more traditional type-1 fuzzy sets. Because of this, in many practical applications, the use of type-2 fuzzy sets has led to better quality control, better quality clustering, etc. The main reason why they are not universally used is that when we go from type-1 sets to type-2 sets, the computational time of data processing increases.

For the practically important case of interval-valued fuzzy numbers, processing of such such data can be reduced to processing interval data – and is, thus, (almost) as fast as processing type-1 fuzzy data. In this paper, we argue that these reduction techniques can be extended to arbitrary type-2 fuzzy numbers – and thus, that processing general type-2 fuzzy numbers is also (almost) as fast as processing type-1 fuzzy data.

This result will hopefully lead to more practical applications of type-2 fuzzy sets – which more adequately describe expert knowledge.

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